36th AIAA Thermophysics Conference - Orlando, Florida, June 23 - 26, 2003

Thermal Contact Resistance of Non-Conforming Rough Surfaces Part 1: Contact Mechanics Model

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- present model
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- approximate model (dimensional analysis and correlations)
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OBJECTIVES



- develop analytical model to predict contact parameters such as pressure distribution and size of the macrocontact area
- derive simple correlations for determining contact parameters used in analytical thermal contact models
- criterion to define a "flat surface"

INTRODUCTION



- contact of two spherical rough surfaces includes two problems:
 - microcontacts deformation or micro scale problem
 - bulk deformation or macro scale problem
- macrocontact area is the area in which the microcontacts are distributed



LITERATURE REVIEW



- microcontact modeling
 - Gaussian roughness
 - equivalent rough surface

 $\sqrt{\begin{array}{ccc} 2 & 2 \\ 1 & 2 \end{array}}$ and $m \sqrt{m_1^2 & m_2^2}$

- microhardness
 - Vickers microhardness correlation, Hegazy (1985)
 - $H_v \quad c_1 \ d_v \quad c_2$
- macrocontact modeling
 - equivalent radius of curvature, Hertz (1881)



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COOPER ET AL. MODEL

- conforming rough contacts
- Gaussian distribution for asperity
- plastically deformed hemispherical asperities



 $Y/\sqrt{2}$

a) section through two contacting surfaces

b) corresponding section through equivalent rough - smooth flat

$$\frac{A_r}{A_a}$$
 $\frac{1}{2}$ erfc

$$a_s \sqrt{\frac{8}{m}} \exp^2 \operatorname{erfc}^2$$

$$n_s \quad \frac{1}{16} \quad \frac{m}{2} \quad \frac{2 \exp\left(-2^{-2}\right)}{\operatorname{erfc}} A_a$$

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GREENWOOD AND TRIPP (GT) MODEL



- axisymmetric contact; elastic bulk deformation
- rough surfaces are isotropic and have Gaussian height distribution with a standard deviation ρ
- distribution of summit heights is same as surface heights standard deviation, i.e., $\rho_s = \rho$
- the deformation of each asperity is independent of its neighbors
- spherical summits all with constant radius, β; asperities deform elastically and Hertz theory applied for each individual summit.

Waterloo PRESENT MODEL (ASSUMPTIONS)

- surfaces are macroscopically spherical
- microscopically, surfaces are rough with a Gaussian asperity distribution
- microcontacts deform plastically
- elastic macrocontact
- first loading Y



 $r^{2}/2$ u r u_0

$$r r b r - u r b r - u_0 r^2/2$$

$$u v u_0 - v'$$



GOVERNING RELATIONSHIPS

$$Y r \qquad {}_{b} r - u r \qquad {}_{b} r - u_{0} r^{2}/2 \qquad \text{rigid sphere} \qquad F$$

$$a_{s} r \qquad \sqrt{\frac{8}{m}} \exp^{-2} r \quad \text{erfc} r$$

$$H_{mic} r \qquad c_{1} \left[\sqrt{2} a_{s} r\right]^{c_{2}} \qquad \qquad f_{1} \qquad f$$

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NUMERICAL RESULTS

	25 mm	F 50 N
	1.41 m	E 112.1 GPa
т	0.107 -	c_1/c_2 6.27 <i>GPa</i> / -0.15 -



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NUMERICAL RESULTS (Cont'd)



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EFFECT OF ROUGHNESS



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APPROXIMATE MODEL

- effective microhardness, H_{mic} = Const.
- surface slope *m* is assumed to be a function of surface roughness, Lambert (1995)

 $m = 0.076^{-0.52}$

• maximum contact pressure is a function of

 $P_0 \quad P_0 \quad , \quad ,E , F, H_{mic}$

• Hertzian pressure distribution is

$$P_{Hz} r/a_{Hz} P_{0,Hz} \sqrt{1 - r/a_{Hz}^2}$$

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GENERAL PRESSURE DISTRIBUTION



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DIMENSIONAL ANALYSIS

Parameter	Dimension
Effective elastic modulus, E	$ML^{-1}T^{-2}$
Force, F	MLT ⁻²
Microhardness, H_{mic}	$ML^{-1}T^{-2}$
Radius of curvature,	М
Roughness,	M
Max. contact pressure, P_0	$ML^{-1}T^{-2}$

three non-dimensional parameters

$$\frac{16}{0,H_z} = \frac{16}{a_{H_z}^2} \left(\frac{16}{9F^2}\right)^{1/3}$$

$$\frac{1}{a_{H_z}} = \left[\frac{4E}{3F}\right]^{1/3}$$

$$E = \frac{E}{H_{mic}}$$

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EFFECT OF MICROHARDNESS



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MAXIMUM CONTACT PRESSURE



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RADIUS OF MACROCONTACT



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CORRELATIONS



$$P_{0} \quad \frac{P_{0}}{P_{0,Hz}} \quad \frac{1}{1 \, 1.37} \, {}^{-0.075}$$

$$a_{L} \quad \frac{a_{L}}{a_{Hz}} \quad 1 - 1.50 \ln P_{0} - 0.14 \ln^{2} P_{0} - 0.111 \ln^{3} P_{0}$$

Or,

$$a_L \quad \frac{a_L}{a_{Hz}} \quad 1.80 \frac{\sqrt{0.31^{0.056}}}{0.028}$$

$$P \qquad P_0 \ 1 \ - \ ^2$$

using a force balance, $F = 2 = \frac{a_L}{0}P r r dr$

$$1.5P_0 a_L^2 - 1$$

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ELASTIC COMPRESSION

critical force F_c , $a_L = b_L$

$$F_c = \frac{4E}{3} \max 0, \ b_L^2 - 2.25$$

 uniform increase will be added to critical pressure distribution at each point



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FLAT SURFACE



 a_L 1.5 $\sqrt{0.45}$ and a_L b_L $F_c = 0$

if the out-of-flatness and the roughness of a surface are in the same order of magnitude, the surface is flat,

- 1.12

SUMMARY AND CONCLUSIONS



- closed set of governing relationships was derived and solved numerically
- general pressure distribution was proposed that yields Hertzian pressure at limit, where roughness approaches zero
- using curve-fitting techniques, simple correlations were proposed for calculating contact parameters, as functions of governing non-dimensional parameters
- criterion was derived to identify flat surface

PRESENT MODEL VS GT MODEL



PRESENT MODEL	GT MODEL
elastic bulk plastic microcontacts	elastic bulk plastic microcontacts
requires 2 input surface parameters ρ, <i>m</i>	requires 3 input surface parameters ρ , β , γ_s
input parameters can be measured directly and are not sensitive to measurements	β , γ_s must be calculated through statistical relationships and are sensitive to measurements
simple correlations	requires computer programming and numerically intensive solutions

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NUMERICAL ALGORITHM



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THE INNER LOOP ALGORITHM



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CONTACT PRESSURE DISTRIBUTION



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GT MODEL SHORTCOMINGS



- A constant summit radius β is unrealistic
- Two of its input parameters, i.e., radius of summits β and density of summits γ_s cannot be measured directly and must be estimated through statistical calculations. These parameters are sensitive to the surface measurements
- Applying the model is complex and requires computer programming and numerically intensive solutions
- All asperities are assumed to deform elastically.