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THERMAL SPREADER FOR COOLING
MICROELECTRONIC DEVICES

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**CIRCULAR AND ANNULAR CONSTRICTION RESISTANCES
WITHIN A COMPOUND THERMAL SPREADER FOR
COOLING MICROELECTRONIC DEVICES**

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Abstract

Analytical solutions of the steady-state temperature distributions as well as the one-dimensional and two-dimensional (constriction) resistances were obtained for a compound thermal spreader which has a circular heat source (device) on one face and an annular sink on the other face. The resistances were found to be functions of several thermal and geometric parameters. The results of a parametric study are given in graphical form for a range of the parameters which are of some interest to the device thermal analyst.

Nomenclature

- a = device radius
- $A_n^{(i)}$ = Fourier coefficients (i=1,2)
- b = sink inner radius
- $B_n^{(i)}$ = Fourier coefficients (i=1,2)
- c = thermal spreader radius
- $C_1^{(i)}, C_2^{(i)}$ = Fourier coefficients (i=1,2)
- $J_0(\cdot), J_1(\cdot)$ = Bessel functions of the first kind of order zero and one
- k_1, k_2 = thermal conductivities
- $q_1(r)$ = device heat flux distribution
- q_0 = sink heat flux
- Q = heat flow rate
- r, z = polar coordinates
- R_{LD} = one-dimensional resistance
- R_c = constriction resistance
- R_T = total resistance ($R_T = R_{LD} + R_c$)
- R^* = dimensionless resistance ($R^* = 4k_1 aR$)
- t_1, t_2, t = thickness of each component ($t = t_1 + t_2$)
- T_1, T_2 = temperature distributions
- $\bar{T}_{so}, \bar{T}_{si}$ = average temperatures of heat source and sink

Greek Symbols

- γ = b/c
- δ_n = roots of $J_1(\delta_n) = 0$
- ϵ = a/c
- κ = k_1/k_2
- λ_n = separation constants where $J_1(\lambda_n c) = 0$
- π = pi
- τ_1, τ_2, τ = $t_1/c, t_2/c, (\tau = t_1 + t_2)$

Introduction

There are two primary objectives in the thermal design of microelectronic equipment. The first is to ensure, during worst case operating conditions, that all component temperatures are maintained below specified maximum functional limits. The second objective is to ensure, during nominal operating conditions, that the relatively lower component temperature reliability requirement is satisfied. Successful thermal management requires an accurate determination of the individual thermal resistances inherent in the package, including the often crucial thermal contact and constriction resistances associated with the microelectronic devices found within modern high speed computers.

Thermal Constriction (Spreading) Resistance

Heat transfer from a semiconductor junction is often modelled as a small singly-connected planar heat source of some simple shape (circular, square, rectangular, etc.) in perfect contact with a chip which is assumed to be a semi-infinite body [1,2]. Furthermore, it is assumed that the thermal energy generated by the semiconductor is released uniformly over the junction area. As shown in Fig. 1, heat flows from the junction through the chip, spreads in some complex manner and leaves the chip through some interface located at a distance which is large relative to the characteristic dimension of the junction area. This spreading of the heat flow lines gives rise to a spreading (or constriction) resistance. The maximum temperature within the junction area will occur at or near the centroid of the junction area, depending upon whether it is symmetric or nonsymmetric. The average junction temperature will always be below the centroidal temperature for all geometries [3,4].

The spreading (or constriction) resistance is defined as the temperature difference between the average junction temperature and some reference temperature, divided by the total heat flow rate from the junction. It should be noted that an

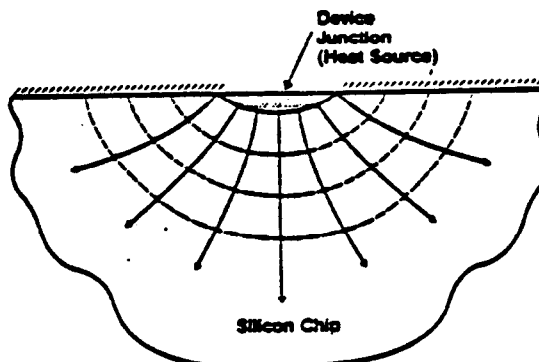


Fig. 1 Device junction on half-space

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$$4) z=c_1, \quad 0 \leq r \leq c, \quad T_1 = T_2 \quad (5a)$$

$$k_1 \frac{\partial T_1}{\partial z} = k_2 \frac{\partial T_2}{\partial z} \quad (5b)$$

$$5) z=c_1+c_2, \quad 0 \leq r < b, \quad \frac{\partial T_2}{\partial z} = 0 \quad (6a)$$

$$b < r \leq c, \quad \frac{\partial T_2}{\partial z} = \frac{-q_0}{k_2} \quad (6b)$$

with $q_0 = Q/\pi(c^2-b^2)$ and Q is the total heat flow rate from the device.

By the method of separation of variables and the superposition principle, the two temperature distributions can be expressed as

$$T_1 = C_1^{(1)} + C_2^{(1)}z + \sum_{n=1}^{\infty} [A_n^{(1)} \cosh(\lambda_n z) + B_n^{(1)} \sinh(\lambda_n z)] J_0(\lambda_n r) \quad (7)$$

and

$$T_2 = C_1^{(2)} + C_2^{(2)}z + \sum_{n=1}^{\infty} [A_n^{(2)} \cosh(\lambda_n z) + B_n^{(2)} \sinh(\lambda_n z)] J_0(\lambda_n r) \quad (8)$$

where $J_0(\cdot)$ is the Bessel function of the first kind of order zero. The Bessel function of the second kind of order zero, $Y_0(\cdot)$, was eliminated to satisfy the boundedness condition along the axis $r=0$.

The separation constants λ_n appearing in both equations are the positive roots of

$$J_1(\lambda_n c) = 0 \quad (9)$$

where $J_1(\cdot)$ is the Bessel function of the first kind of order one.

The first two terms of Eqs. (7) and (8) represent the linear temperature distribution corresponding to $\lambda=0$. The terms under the summation sign represent the spreading or constriction of the heat flow lines due to the circular device (heat source) and the annular area (heat sink).

The temperature gradients in the z -direction will be required and are therefore given:

$$\frac{\partial T_1}{\partial z} = C_2^{(1)} + \sum_{n=1}^{\infty} \lambda_n [A_n^{(1)} \sinh(\lambda_n z) + B_n^{(1)} \cosh(\lambda_n z)] J_0(\lambda_n r) \quad (10)$$

and

$$\frac{\partial T_2}{\partial z} = C_2^{(2)} + \sum_{n=1}^{\infty} \lambda_n [A_n^{(2)} \sinh(\lambda_n z) + B_n^{(2)} \cosh(\lambda_n z)] J_0(\lambda_n r) \quad (11)$$

Since the linear and two-dimensional temperature distributions are independent, the boundary conditions can be applied separately to obtain the Fourier coefficients appearing in Eqs. (7) and (8).

For the linear temperature distribution it can

be shown that $C_1^{(1)}$ is the average temperature of the surface $z=0$, i.e.,

$$\bar{T}_0 = \frac{1}{\pi c^2} \int_0^c T(r,0) 2\pi r dr = C_1^{(1)} \quad (12)$$

Also $C_2^{(1)}$ is determined by

$$q = -k_1 \frac{\partial T_1}{\partial z} = -k_1 C_2^{(1)} = \frac{Q}{\pi c^2} \quad (13)$$

so that

$$C_2^{(1)} = -\frac{Q}{k_1 \pi c^2} \quad (14)$$

The perfect contact conditions along $z=c_1$ require

$$k_1 C_2^{(1)} = k_2 C_2^{(2)} \quad (15)$$

so that

$$C_2^{(2)} = -\frac{Q}{k_2 \pi c^2} \quad (16)$$

and

$$C_1^{(1)} + C_2^{(1)} c_1 = C_1^{(2)} + C_2^{(2)} c_1 \quad (17)$$

so that

$$C_1^{(2)} = \bar{T}_0 - \frac{Qc_1}{\pi c^2} \left[\frac{1}{k_1} - \frac{1}{k_2} \right] \quad (18)$$

The linear temperature distributions are therefore

$$T_1 = \bar{T}_0 - \frac{Qz}{k_1 \pi c^2} \quad 0 \leq z \leq c_1 \quad (19)$$

and

$$T_2 = \bar{T}_0 - \frac{Qc_1}{\pi c^2} \left[\frac{1}{k_1} - \frac{1}{k_2} \right] - \frac{Qz}{k_2 \pi c^2} \quad c_1 \leq z \leq c_1+c_2 \quad (20)$$

The one-dimensional thermal resistance of the compound thermal spreader can be determined by means of the following definition:

$$QR_{1D} = \bar{T}_0 - \bar{T}_c \quad (21)$$

where

$$\bar{T}_c = \frac{1}{\pi c^2} \int_0^c T(r,c) 2\pi r dr$$

Therefore,

$$R_{1D} = \frac{1}{\pi c^2} \left[\frac{c_1}{k_1} + \frac{c_2}{k_2} \right] \quad (22)$$

For the two-dimensional temperature distributions the perfect contact conditions along $z=c_1$ require

$$A_n^{(1)} \cosh(\lambda_n c_1) + B_n^{(1)} \sinh(\lambda_n c_1) = A_n^{(2)} \cosh(\lambda_n c_1) + B_n^{(2)} \sinh(\lambda_n c_1) \quad (23)$$

$$\text{and } k_1 [A_n^{(1)} \sinh(\lambda_n c_1) + B_n^{(1)} \cosh(\lambda_n c_1)] =$$

$$k_2 [A_n^{(2)} \sinh(\lambda_n c_1) + B_n^{(2)} \cosh(\lambda_n c_1)] \quad (24)$$

$$\begin{aligned}
 & A_n^{(1)} \cosh(\delta_n \tau_1) + B_n^{(1)} \sinh(\delta_n \tau_1) = \\
 & A_n^{(2)} \cosh(\delta_n \tau_1) + B_n^{(2)} \sinh(\delta_n \tau_1) \quad (42)
 \end{aligned}$$

$$\begin{aligned}
 & \kappa [A_n^{(1)} \sinh(\delta_n \tau_1) + B_n^{(1)} \cosh(\delta_n \tau_1)] = \\
 & A_n^{(2)} \sinh(\delta_n \tau_1) + B_n^{(2)} \cosh(\delta_n \tau_1) \quad (43)
 \end{aligned}$$

The total constriction resistance, Eq. (36), becomes

$$R_c^* = 2 \sum_{n=1}^{\infty} A_n^{(1)} \frac{J_1(\delta_n \epsilon)}{(\delta_n \epsilon)} +$$

$$\frac{2\gamma^2}{(1-\gamma^2)} \sum_{n=1}^{\infty} [A_n^{(2)} \cosh(\delta_n \tau) + B_n^{(2)} \sinh(\delta_n \tau)] \frac{J_1(\delta_n \gamma)}{(\delta_n \gamma)} \quad (44)$$

The simultaneous solution of Eqs. (40) through (43) with Eq. (44) gives us the total dimensionless constriction which is seen to be dependant upon ϵ , γ , κ , τ_1 and τ or

$$R_c^* = R_c^*(\epsilon, \gamma, \kappa, \tau_1, \tau) \quad (45)$$

Parametric Study and Results

As shown in the previous section the dimensionless total constriction resistance depends upon several geometric and thermal parameters. To illustrate the effect of these parameters for a typical microelectronics application without having to resort to numerous graphs, another parameter was introduced which is the ratio of the total constriction resistance for a unit disk $\tau=\tau_1$ to the total constriction resistance of the same unit disk of conductivity $k_2 = k_1$ and full sink area, $b=0$, thus

$$R^* = \frac{R_c^*(\epsilon, \gamma, \kappa, \tau_1, \tau=1)}{R_c^*(\epsilon, \gamma=0, \kappa=1, \tau_1=\tau)} \quad (46)$$

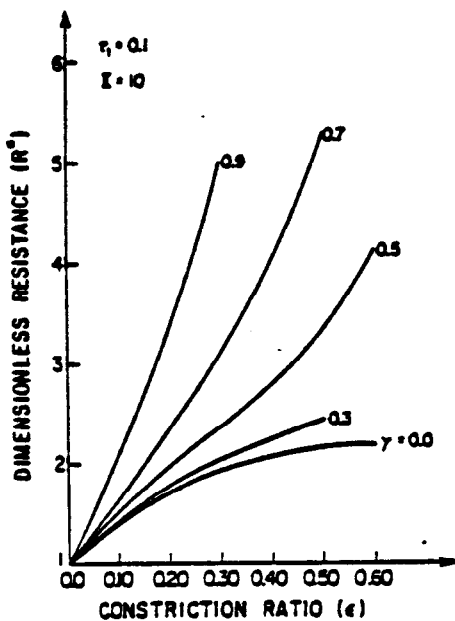


Fig. 4 Effect of several geometric parameters upon the dimensionless resistance for silicon on kovar

This parameter, called the dimensionless resistance, was computed for $\kappa=10$ which corresponds to the case of silicon in contact with kovar for an interesting range of the parameters ϵ , γ and τ_1 . The results of the study are given in Figs. 4 through 8.

We observe that when $\tau_1=0.1$, R^* is considerably greater than one for all values of $\gamma > 0$ when $\epsilon > 0.3$. This is due primarily to the constriction resistance of the thermal sink and the lower conductivity of the kovar. As τ_1 increases, the dimensionless resistance R^* decreases approaching

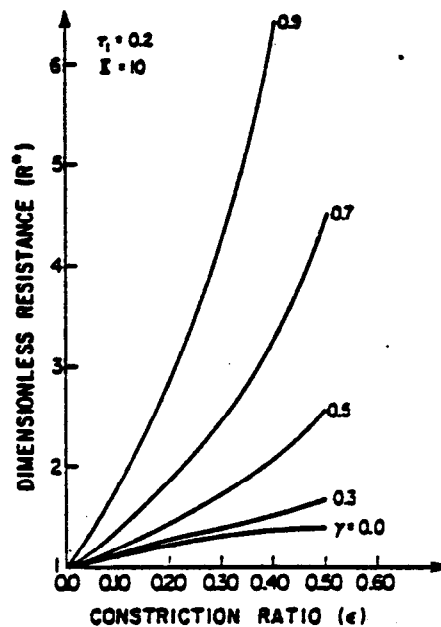


Fig. 5 Effect of several geometric parameters upon the dimensionless resistance for silicon on kovar

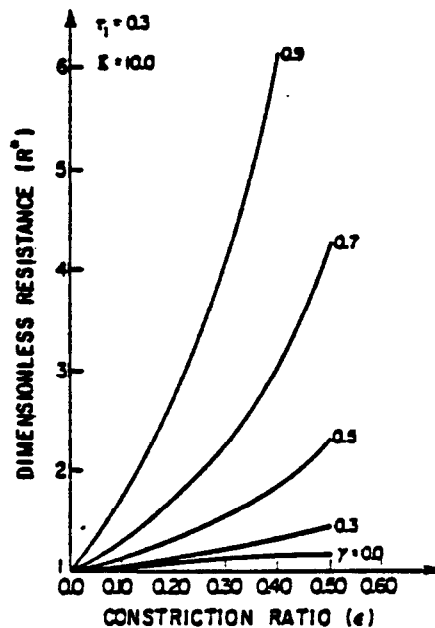


Fig. 6 Effect of several geometric parameters upon the dimensionless resistance for silicon on kovar

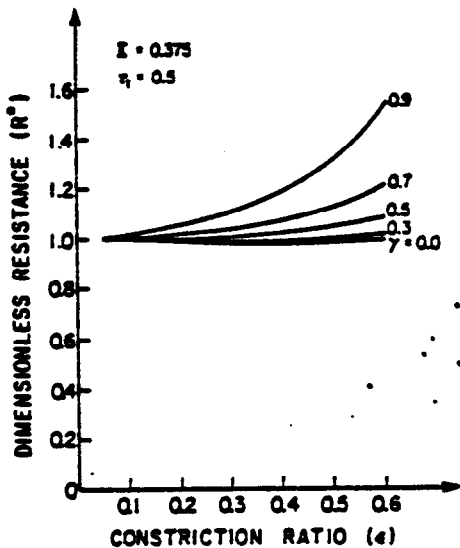


Fig. 11 Effect of copper or gold substrates upon the dimensionless resistance when $\tau_1=0.1$

Fig. 12 shows the effect of τ_1 upon R^* when $\kappa=0.375$ and $\gamma=0.9$ for a range of values of ϵ . It can be seen that when $\tau_1 > 0.2$, $R^* > 1$ for all ϵ , but when $\tau_1 < 0.2$, $R^* < 1$ for $\epsilon < 0.5$. The greatest decrease in R^* occurs when $0.2 < \epsilon < 0.3$ for $\tau_1 = 0.1$.

The graphical results given in Figs. 4 through 12 illustrate how the analytical solution can be used to demonstrate the effect of the several geometric and thermal parameters which influence the total dimensionless constriction resistance of a compound thermal spreader.

Conclusions

An analytical solution has been presented for steady conduction through a compound thermal spreader. By means of the expression developed for the dimensionless total constriction resistance a parametric study was undertaken to demonstrate how the various parameters influence the resistance for typical ranges of the parameters such as conductivity ratio, relative device size, relative sink size and the relative thicknesses of the chip and substrate.

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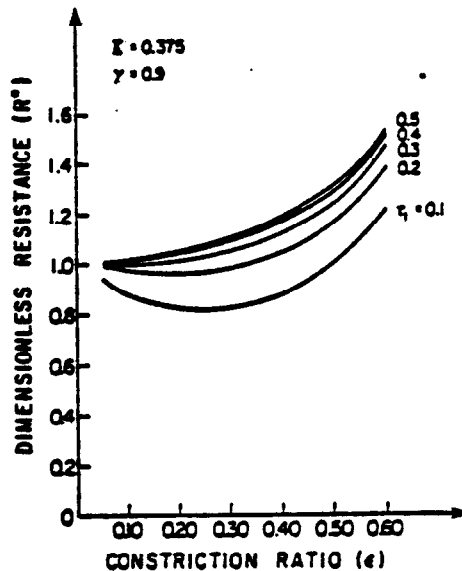


Fig. 12 Effect of sink when silicon is on a copper or gold substrate

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